

# SVENSK STANDARD

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### **Maskinsäkerhet – Ergonomiska krav på utformning av avläsningsinstrument (display) och manövreringsorgan – Del 1: Allmänna principer för samspelet människa – avläsningsinstrument – manövreringsorgan**

### **Safety of machinery – Ergonomics requirements for the design of displays and control actuators – Part 1: General principles for human interactions with displays and control actuators**

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Denna standard ersätter SS-EN 894-1, utgåva 1.

The European Standard EN 894-1:1997+A1:2008 has the status of a Swedish Standard. This document contains the official English version of EN 894-1:1997+A1:2008.

This standard supersedes the Swedish Standard SS-EN 894-1, edition 1.

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EUROPEAN STANDARD

**EN 894-1:1997+A1**

NORME EUROPÉENNE

EUROPÄISCHE NORM

October 2008

ICS 13.110; 13.180

Supersedes EN 894-1:1997

English Version

## Safety of machinery - Ergonomics requirements for the design of displays and control actuators - Part 1: General principles for human interactions with displays and control actuators

Sécurité des machines - Spécifications ergonomiques pour la conception des dispositifs de signalisation et des organes de service - Partie 1: Principes généraux des interactions entre l'homme et les dispositifs de signalisation et organes de service

Sicherheit von Maschinen - Ergonomische Anforderungen an die Gestaltung von Anzeigen und Stellteilen - Teil 1: Allgemeine Leitsätze für Benutzer-Interaktion mit Anzeigen und Stellteilen

This European Standard was approved by CEN on 3 January 1997 and includes Amendment 1 approved by CEN on 14 August 2008.

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## Foreword

This document (EN 894-1:1997+A1:2008) has been prepared by Technical Committee CEN/TC 122 “Ergonomics”, the secretariat of which is held by DIN.

This European Standard shall be given the status of a national standard, either by publication of an identical text or by endorsement, at the latest by April 2009, and conflicting national standards shall be withdrawn at the latest by December 2009.

This document includes Amendment 1, approved by CEN on 2008-08-14.

This document supersedes EN 894-1:1997.

The start and finish of text introduced or altered by amendment is indicated in the text by tags A1 A1

This European Standard has been prepared under a mandate given to CEN by the European Commission and the European Free Trade Association, and supports essential requirements of EU Directive(s).

A1 For relationship with EU Directive(s), see informative Annexes ZA and ZB, which are integral parts of this document. A1

According to the CEN/CENELEC Internal Regulations, the national standards organizations of the following countries are bound to implement this European Standard: Austria, Belgium, Bulgaria, Cyprus, Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland and United Kingdom.

## SS-EN 894-1+A1:2008 (E)

# Introduction

This standard has been prepared to be a harmonized standard in the sense of the Machinery Directive and associated EFTA regulations.

## 1 Scope

This European Standard applies to the design of displays and control actuators on machinery. It specifies general principles for human interaction with displays and control actuators, to minimise operator errors and to ensure an efficient interaction between the operator and the equipment. It is particularly important to observe these principles when an operator error may lead to injury or damage to health.

## 2 Normative references

This European Standard incorporates by dated or undated reference, provisions from other publications. These normative references are cited at the appropriate places in the text and the publications are listed hereafter. For dated reference subsequent amendments to, or revisions of, any of these publications apply to this European Standard only when incorporated in it by amendment or revision. For undated references the latest edition of the publication referred to applies.

EN 292-1, *Safety of machinery - Basic concepts, general principles for design - Part 1: Basic terminology, methodology.*

EN 292-2, *Safety of machinery - Basic concepts, general principles for design - Part 2: Technical principles and specifications.*

EN 418, *Safety of machinery – Emergency stop equipment, functional aspects – Principles for design.*

EN 614-1, *Safety of machinery – Ergonomics design principles – Part 1: Terminology and general principles.*

prEN 894-2, *Safety of machinery – Ergonomics requirements for the design of displays and control actuators – Part 2: Displays.*

prEN 894-3, *Safety of machinery – Ergonomics requirements for the design of displays and control actuators – Part 3: Control actuators.*

EN ISO 9241-10, *Ergonomic requirements for office work with visual display terminals (VDTs) – Part 10: Dialogue principles.*

## 3 Definitions

For the purposes of this European Standard, the following definitions apply:

### 3.1

#### **control actuator**

the part of the control actuating system that is directly actuated by the operator, e.g. by applying pressure



### **3.2**

#### **display**

device for presenting information that can change with the aim of making things visible, audible or discriminable by touch (tactile)

### **3.3**

#### **operator**

the person or persons given the task of installing, operating, adjusting, maintaining, cleaning, repairing or transporting machinery [EN 292-1].

## **4 Design principles for operator-task relationships**

Human-machine systems are considered here as closed loops: the machine displays information to the operator who uses control actuators to affect the machine, which in turn provides feedback to the operator, etc.

Human-machine systems can comprise any number of man-machine units or subsystems, in which a single operator interacts with a machine or process. Several subsystems may act independently or interact with each other. When considering the requirements for a particular human-machine subsystem it is important to assess how it interacts with the system as a whole.

Moreover, human-machine systems are part of more complex systems. For example, the physical environment (noise, lighting, etc.) as well as the social and organisational environment can affect the efficient operation of human-machine systems.

Knowledge of ergonomics principles is the basis for a successful implementation of a human-machine system. In particular, it is important to ensure that systems are designed as an iterative process between the designer and the users. EN 614-1 provides a framework for incorporating ergonomics principles in the design process that shall be taken into account when designing machines. This framework can help designers to take account of the principles in this standard.

An important factor to consider is the degree to which the human operator is needed in the system in order to accomplish the given task. The informative annex A summarizes information on the capabilities of humans when interacting with machines. The designer shall consider if the planned allocation of a particular function in a man-machine system is in accordance with human capabilities. If this is not the case, the designer shall redesign the system. A result of the redesign may be a (sub) system without the involvement of an operator.

The overall principle which concerns human-machine systems is that the machine and its associated elements (displays, controls, instructions, etc) shall be suitable for the operator and the given task. In order to realise this general principle, the machine system shall be so designed that human characteristics with respect to physical, psychological and social aspects are considered. The following clauses present ergonomics principles that shall be considered when designing a human-machine system. Some guidance on methods which can be used to achieve the principles is also given. It should be noted that this list is not exhaustive but provides a good indication of practical measures which should be considered. EN ISO 9241-10 gives further information on these principles when applied to software.

When trying to comply with these requirements it is important that the selected solutions shall be tested under realistic conditions (see EN 614-1).

### **4.1 Suitability for the task**

A human-machine system is suitable for the task if it supports the operator in the safe, effective and efficient completion of the task.

## SS-EN 894-1+A1:2008 (E)

### 4.1.1 Principle of function allocation

The most suitable allocation of functions between the operator and the machine should be decided after considering the requirements of the task and the strengths and limitations of the human operator.

#### Application:

Ensure the machine does not place unacceptable demands on the operator in terms of, for example, speed and accuracy of response, forces required to operate control actuators, vigilance for small changes in display status.

### 4.1.2 Principle of complexity

As far as consistent with the task requirements, possibilities shall be offered to reduce complexity. Special consideration shall be given to the complexity of the task structure and the type and amount of the information to be processed by the operator.

#### Application:

When designing human-machine interaction then speed and accuracy are important variables to consider. Those factors which influence these variables need to be determined.

For example, in check reading, the operator makes a qualitative assessment that the system is within acceptable boundaries. The accuracy of such readings may be enhanced if the pointers of the displays are arranged into a pattern so that it is easy to determine if one or several of the pointers deviate from the normal pattern (see prEN 894-2).

### 4.1.3 Principle of grouping

Arrange displays and control actuators so that they are easy to use in combination by following procedures for grouping items.

#### Application:

Where control actuators and displays are operated in a certain fixed sequence, they shall be arranged in that sequence. This arrangement helps the operator to remember the sequence and it decreases response time and leads to fewer errors.

Where control actuators and displays are not operated in a fixed sequence then the grouping should be determined using the following aspects:

- a) The importance for the safe use of the machine;
- b) The frequency of use in regular machine operation;
- c) The use of elements in a sub-sequence (for example, start up controls like the ignition, choke and starter on a car);
- d) The functional relationship between elements (for example, the wiper and wash controls on a car).

The above aspects are not mutually exclusive and several elements may appear in more than one category.

Consequently the location of displays and control actuators should be arranged so that:

- a) The important and frequently used items are in the most accessible positions;
- b) Items in sub-sequences are then placed together;

c) Functionally related items are placed in groups with visual and spatial separation from other items.

Important displays and control actuators, such as those used for emergencies shall be designed and positioned so that they can be used quickly and accurately. Guidance on emergency stop devices is given in EN 418.

#### **4.1.4 Principle of identification**

Control actuators and displays should be readily identifiable.

##### **Application:**

Labels, signs and other informative texts or symbols should be located on or adjacent to their associated control actuators and displays in such a position that they are visible when the control actuators are operated. It is generally preferable to place such means of identification either above or on the control actuator or display.

#### **4.1.5 Principle of operational relationship**

Associated control actuators and displays should be arranged to reflect their operational relationships.

##### **Application:**

Control actuators should be located adjacent to associated displays so as to make their relationship obvious to the operator.

The direction of control actuator operation shall be consistent with the direction of associated system responses and/or display movements (see prEN 894-2 and prEN 894-3).

If a system failure occurs, it shall be identified to the operator as quickly as possible.

## **4.2 Self-descriptiveness**

The human-machine interface should be designed so as to be self-descriptive, this means that the operator can easily recognise the displays and controls and understand the underlying process.

#### **4.2.1 Principle of information availability**

Information about the status of the system shall be readily available at the request of the operator without the need to interfere with other activities.

##### **Application:**

Verification that an operator action has been accepted by the system shall be presented to the operator without unnecessary delay. If the execution is prolonged, the operator should be informed. When appropriate the system shall respond instantly and simultaneously to an operator's actuation of the associated control actuator. With delays greater than 1 s, the perceived association is reduced and preliminary feedback becomes necessary.

## **4.3 Controllability**

The operator shall dominate the system. This means that the system and its components shall guide the operator throughout the task during periods when the system is under direct operator control. The operator shall not be dominated by the workcycle rhythm inherent in the system.